

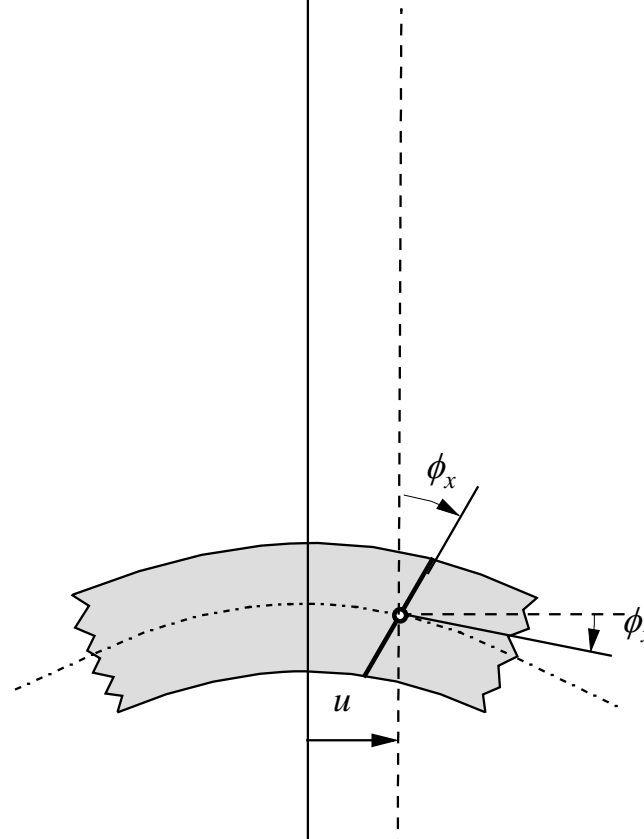
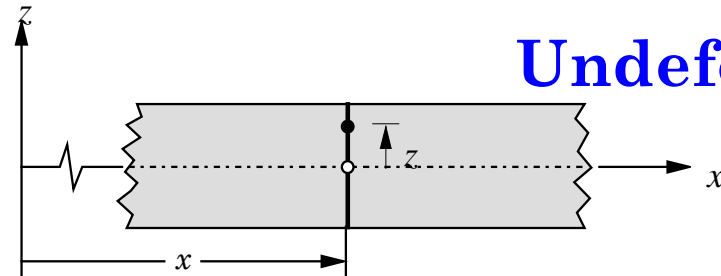
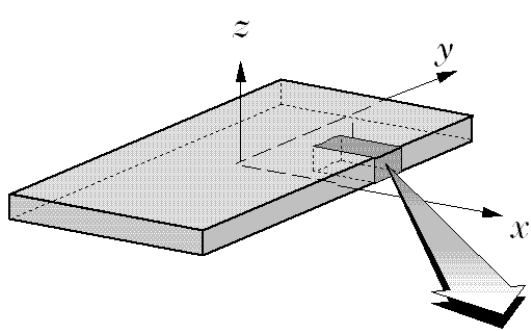


# **FINITE ELEMENT MODELS OF NONLINEAR PLATE BENDING**

## **CONTENTS**

- **Finite element models of the FSDT**
- **Shear and Membrane Locking**
- **Numerical Examples**

# Kinematics of the Classical and Shear Deformation Plate Theories



# GOVERNING EQUATIONS OF THE FSDT

## with the *von Karman Nonlinearity*

### Nonlinear strains

$$\varepsilon_{ij} = \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} + \frac{\partial u_m}{\partial x_i} \frac{\partial u_m}{\partial x_j} \right)$$

$$\varepsilon_{xx} = \frac{\partial u_1}{\partial x_1} + \frac{1}{2} \frac{\partial u_m}{\partial x_1} \frac{\partial u_m}{\partial x_1} = \frac{\partial u_1}{\partial x_1} + \frac{1}{2} \left( \frac{\partial u_1}{\partial x_1} \right)^2 + \frac{1}{2} \left( \frac{\partial u_2}{\partial x_1} \right)^2 + \frac{1}{2} \left( \frac{\partial u_3}{\partial x_1} \right)^2$$

### Von Karman Nonlinear strains

$$\varepsilon_{xx} = \frac{\partial u_1}{\partial x} + \frac{1}{2} \left( \frac{\partial u_3}{\partial x} \right)^2 = \frac{\partial u}{\partial x} + \frac{1}{2} \left( \frac{\partial w}{\partial x} \right)^2 + z \frac{\partial \phi_x}{\partial x}, \quad \gamma_{xz} = \frac{\partial w}{\partial x} + \phi_x$$

$$\varepsilon_{yy} = \frac{\partial u_2}{\partial y} + \frac{1}{2} \left( \frac{\partial u_3}{\partial y} \right)^2 = \frac{\partial v}{\partial y} + \frac{1}{2} \left( \frac{\partial w}{\partial y} \right)^2 + z \frac{\partial \phi_y}{\partial y}, \quad \gamma_{yz} = \frac{\partial w}{\partial y} + \phi_y$$

$$\gamma_{xy} = \frac{\partial u_1}{\partial y} + \frac{\partial u_2}{\partial x} + \frac{\partial u_3}{\partial x} \frac{\partial u_3}{\partial y} = \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} + \frac{\partial w}{\partial x} \frac{\partial w}{\partial y} + z \left( \frac{\partial \phi_x}{\partial y} + \frac{\partial \phi_y}{\partial x} \right)$$

# EQUATIONS OF MOTION OF FSDT

$$\frac{\partial N_{xx}}{\partial x} + \frac{\partial N_{xy}}{\partial y} + f_x = I_0 \frac{\partial^2 u}{\partial t^2} + I_1 \frac{\partial^2 \phi_x}{\partial t^2}$$

$$\frac{\partial N_{xy}}{\partial x} + \frac{\partial N_{yy}}{\partial y} + f_y = I_0 \frac{\partial^2 v}{\partial t^2} + I_1 \frac{\partial^2 \phi_y}{\partial t^2}$$

$$\begin{aligned} \frac{\partial Q_x}{\partial x} + \frac{\partial Q_y}{\partial y} + \frac{\partial}{\partial x} \left( N_{xx} \frac{\partial w}{\partial x} + N_{xy} \frac{\partial w}{\partial y} \right) \\ + \frac{\partial}{\partial y} \left( N_{xy} \frac{\partial w}{\partial x} + N_{yy} \frac{\partial w}{\partial y} \right) + q = I_0 \frac{\partial^2 w}{\partial t^2} \end{aligned}$$

$$\frac{\partial M_{xx}}{\partial x} + \frac{\partial M_{xy}}{\partial y} - Q_x = I_2 \frac{\partial^2 \phi_x}{\partial t^2} + I_1 \frac{\partial^2 u}{\partial t^2}$$

$$\frac{\partial M_{xy}}{\partial x} + \frac{\partial M_{yy}}{\partial y} - Q_y = I_2 \frac{\partial^2 \phi_y}{\partial t^2} + I_1 \frac{\partial^2 v}{\partial t^2}$$

# FINITE ELEMENT MODELS OF (FSDT)

## Weak Forms (from the principle of virtual displacements)

$$0 = \int_{\Omega^e} \left( \frac{\partial \delta u}{\partial x} N_{xx} + \frac{\partial \delta u}{\partial y} N_{xy} - \delta u f_x + I_0 \delta u \frac{\partial^2 u}{\partial t^2} \right) dx dy - \oint_{\Gamma^e} \delta u_n N_{nn} ds$$

$$0 = \int_{\Omega^e} \left( \frac{\partial \delta v}{\partial x} N_{xy} + \frac{\partial \delta v}{\partial y} N_{yy} - \delta v f_y + I_0 \delta v \frac{\partial^2 v}{\partial t^2} \right) dx dy - \oint_{\Gamma^e} \delta u_s N_{ns} ds$$

$$0 = \int_{\Omega^e} \left( \frac{\partial \delta w}{\partial x} Q_x + \frac{\partial \delta w}{\partial y} Q_y + \delta w N + I_0 \delta w \frac{\partial^2 w}{\partial t^2} \right) dx dy - \oint_{\Gamma^e} \delta w Q_n ds$$

$$0 = \int_{\Omega^e} \left( \frac{\partial \delta \phi_x}{\partial x} M_{xx} + \frac{\partial \delta \phi_x}{\partial y} M_{xy} + \delta \phi_x Q_x + I_2 \delta \phi_x \frac{\partial^2 \phi_x}{\partial t^2} \right) dx dy - \oint_{\Gamma^e} \delta \phi_n M_{nn} ds$$

$$0 = \int_{\Omega^e} \left( \frac{\partial \delta \phi_y}{\partial x} M_{xy} + \frac{\partial \delta \phi_y}{\partial y} M_{yy} + \delta \phi_y Q_y + I_2 \delta \phi_y \frac{\partial^2 \phi_y}{\partial t^2} \right) dx dy - \oint_{\Gamma^e} \delta \phi_s M_{ns} ds$$

$$Q_n = Q_x n_x + Q_y n_y, \quad M_{nn} = M_{xx} n_x + M_{xy} n_y, \quad M_{ns} = M_{xy} n_x + M_{yy} n_y$$

# THE FIRST-ORDER SHEAR DEFORMATION THEORY

## Stress Resultants (Nonlinear)

$$N_{xx} = A_{11} \left[ \frac{\partial u}{\partial x} + \frac{1}{2} \left( \frac{\partial w}{\partial x} \right)^2 \right] + A_{12} \left[ \frac{\partial v}{\partial y} + \frac{1}{2} \left( \frac{\partial w}{\partial y} \right)^2 \right] + A_{16} \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} + \frac{\partial w}{\partial x} \frac{\partial w}{\partial y} \right) + B_{11} \frac{\partial \phi_x}{\partial x} + B_{12} \frac{\partial \phi_y}{\partial y} + B_{16} \left( \frac{\partial \phi_x}{\partial y} + \frac{\partial \phi_y}{\partial x} \right) - N_{xx}^T$$

$$N_{yy} = A_{12} \left[ \frac{\partial u}{\partial x} + \frac{1}{2} \left( \frac{\partial w}{\partial x} \right)^2 \right] + A_{22} \left[ \frac{\partial v}{\partial y} + \frac{1}{2} \left( \frac{\partial w}{\partial y} \right)^2 \right] + A_{26} \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} + \frac{\partial w}{\partial x} \frac{\partial w}{\partial y} \right) + B_{12} \frac{\partial \phi_x}{\partial x} + B_{22} \frac{\partial \phi_y}{\partial y} + B_{26} \left( \frac{\partial \phi_x}{\partial y} + \frac{\partial \phi_y}{\partial x} \right) - N_{yy}^T$$

$$N_{xy} = A_{16} \left[ \frac{\partial u}{\partial x} + \frac{1}{2} \left( \frac{\partial w}{\partial x} \right)^2 \right] + A_{26} \left[ \frac{\partial v}{\partial y} + \frac{1}{2} \left( \frac{\partial w}{\partial y} \right)^2 \right] + A_{66} \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} + \frac{\partial w}{\partial x} \frac{\partial w}{\partial y} \right) + B_{16} \frac{\partial \phi_x}{\partial x} + B_{26} \frac{\partial \phi_y}{\partial y} + B_{66} \left( \frac{\partial \phi_x}{\partial y} + \frac{\partial \phi_y}{\partial x} \right) - N_{xy}^T$$

# THE FIRST-ORDER SHEAR DEFORMATION THEORY

## Stress Resultants (Nonlinear)

$$M_{xx} = B_{11} \left[ \frac{\partial u}{\partial x} + \frac{1}{2} \left( \frac{\partial w}{\partial x} \right)^2 \right] + B_{12} \left[ \frac{\partial v}{\partial y} + \frac{1}{2} \left( \frac{\partial w}{\partial y} \right)^2 \right] + B_{16} \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) - D_{11} \frac{\partial^2 w}{\partial x^2} - D_{12} \frac{\partial^2 w}{\partial y^2} - 2D_{16} \frac{\partial^2 w}{\partial x \partial y} - M_{xx}^T$$

$$M_{yy} = B_{12} \left[ \frac{\partial u}{\partial x} + \frac{1}{2} \left( \frac{\partial w}{\partial x} \right)^2 \right] + B_{22} \left[ \frac{\partial v}{\partial y} + \frac{1}{2} \left( \frac{\partial w}{\partial y} \right)^2 \right] + B_{26} \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) - D_{12} \frac{\partial^2 w}{\partial x^2} - D_{22} \frac{\partial^2 w}{\partial y^2} - 2D_{26} \frac{\partial^2 w}{\partial x \partial y} - M_{yy}^T$$

$$M_{xy} = B_{16} \left[ \frac{\partial u}{\partial x} + \frac{1}{2} \left( \frac{\partial w}{\partial x} \right)^2 \right] + B_{26} \left[ \frac{\partial v}{\partial y} + \frac{1}{2} \left( \frac{\partial w}{\partial y} \right)^2 \right] + B_{66} \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) - D_{16} \frac{\partial^2 w}{\partial x^2} - D_{26} \frac{\partial^2 w}{\partial y^2} - 2D_{66} \frac{\partial^2 w}{\partial x \partial y} - M_{xy}^T$$

$$Q_x = K_s A_{55} \left( \phi_x + \frac{\partial w}{\partial x} \right) + K_s A_{45} \left( \phi_y + \frac{\partial w}{\partial y} \right); \quad Q_y = K_s A_{45} \left( \phi_x + \frac{\partial w}{\partial x} \right) + K_s A_{44} \left( \phi_y + \frac{\partial w}{\partial y} \right)$$

# FINITE ELEMENT MODELS OF (FSDT)

(continued)

## Finite element approximation

$$u \approx \sum_{j=1}^m u_j(t) \psi_j^{(0)}(x, y), \quad v \approx \sum_{j=1}^m v_j(t) \psi_j^{(0)}(x, y)$$

$$w(x, y, t) = \sum_{j=1}^m w_j(t) \psi_j^{(1)}(x, y)$$

$$\phi_x(x, y, t) = \sum_{j=1}^n S_{xj}(t) \psi_j^{(2)}(x, y), \quad \phi_y(x, y, t) = \sum_{j=1}^n S_{yj}(t) \psi_j^{(2)}(x, y)$$

**Although, in general, different degree of interpolation can be used for various field variables, the same degree of interpolation is used for all variables:**

$$\psi_j^{(0)} = \psi_j^{(1)} = \psi_j^{(2)}$$



# FINITE ELEMENT MODELS OF FSDT (continued)

## Semidiscrete finite element model

$$\begin{bmatrix} \mathbf{M}^{11} & \mathbf{0} & \mathbf{0} & \mathbf{M}^{14} & \mathbf{0} \\ \mathbf{0} & \mathbf{M}^{22} & \mathbf{0} & \mathbf{0} & \mathbf{M}^{25} \\ \mathbf{0} & \mathbf{0} & \mathbf{M}^{33} & \mathbf{0} & \mathbf{0} \\ \mathbf{M}^{14} & \mathbf{0} & \mathbf{0} & \mathbf{M}^{44} & \mathbf{0} \\ \mathbf{0} & \mathbf{M}^{25} & \mathbf{0} & \mathbf{0} & \mathbf{M}^{55} \end{bmatrix} \begin{Bmatrix} \ddot{\mathbf{u}} \\ \ddot{\mathbf{v}} \\ \ddot{\mathbf{w}} \\ \ddot{\mathbf{S}}_x \\ \ddot{\mathbf{S}}_y \end{Bmatrix} + \begin{bmatrix} \mathbf{K}^{11} & \mathbf{K}^{12} & \mathbf{K}^{13} & \mathbf{K}^{14} & \mathbf{K}^{15} \\ \mathbf{K}^{21} & \mathbf{K}^{22} & \mathbf{K}^{23} & \mathbf{K}^{24} & \mathbf{K}^{25} \\ \mathbf{K}^{31} & \mathbf{K}^{32} & \mathbf{K}^{33} & \mathbf{K}^{34} & \mathbf{K}^{35} \\ \mathbf{K}^{41} & \mathbf{K}^{42} & \mathbf{K}^{43} & \mathbf{K}^{44} & \mathbf{K}^{45} \\ \mathbf{K}^{51} & \mathbf{K}^{52} & \mathbf{K}^{53} & \mathbf{K}^{54} & \mathbf{K}^{55} \end{bmatrix} \begin{Bmatrix} \mathbf{u} \\ \mathbf{v} \\ \mathbf{w} \\ \mathbf{S}_x \\ \mathbf{S}_y \end{Bmatrix} = \begin{Bmatrix} \mathbf{F}^1 \\ \mathbf{F}^2 \\ \mathbf{F}^3 \\ \mathbf{F}^4 \\ \mathbf{F}^5 \end{Bmatrix}$$

$$M_{ij}^{11} = I_0 M_{ij}, \quad M_{ij}^{22} = M_{ij}^{33} = I_2 M_{ij}, \quad M_{ij} = \int_{\Omega_e} \psi_i \psi_j \, dx \, dy$$

$$K_{ij}^{11} = \int_{\Omega_e} \left( A_{55} \frac{\partial \psi_i}{\partial x} \frac{\partial \psi_j}{\partial x} + A_{44} \frac{\partial \psi_i}{\partial y} \frac{\partial \psi_j}{\partial y} \right) dx \, dy$$

$$K_{ij}^{12} = \int_{\Omega_e} A_{55} \frac{\partial \psi_i}{\partial x} \psi_j \, dx \, dy$$

$$K_{ij}^{13} = \int_{\Omega_e} A_{44} \frac{\partial \psi_i}{\partial y} \psi_j \, dx \, dy$$

Use reduced integration to avoid shear locking

# FINITE ELEMENT MODELS OF FSDT

## (continued)

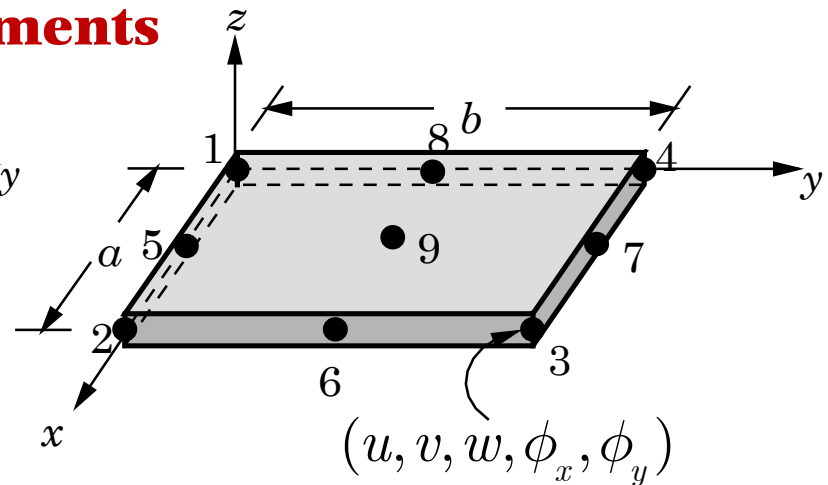
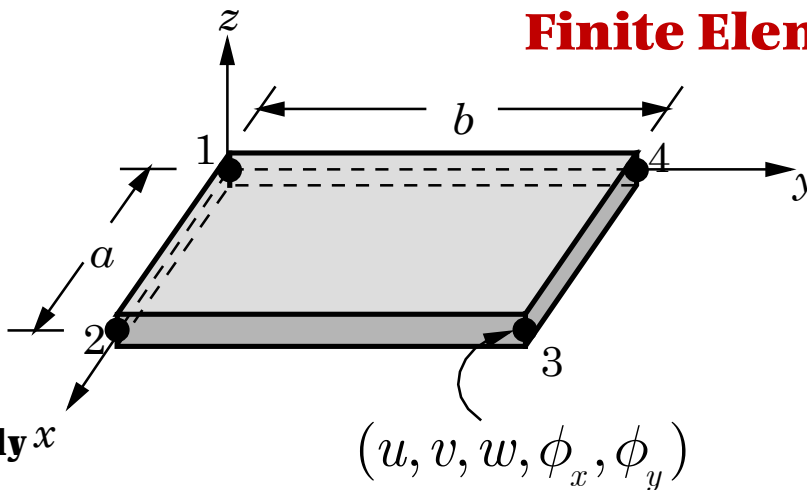
$$K_{ij}^{22} = \int_{\Omega_e} \left( D_{11} \frac{\partial \psi_i}{\partial x} \frac{\partial \psi_j}{\partial x} + D_{66} \frac{\partial \psi_i}{\partial y} \frac{\partial \psi_j}{\partial y} + A_{55} \psi_i \psi_j \right) dx dy$$

$$K_{ij}^{23} = \int_{\Omega_e} \left( D_{12} \frac{\partial \psi_i}{\partial x} \frac{\partial \psi_j}{\partial y} + D_{66} \frac{\partial \psi_i}{\partial y} \frac{\partial \psi_j}{\partial x} \right) dx dy$$

$$K_{ij}^{33} = \int_{\Omega_e} \left( D_{66} \frac{\partial \psi_i}{\partial x} \frac{\partial \psi_j}{\partial x} + D_{22} \frac{\partial \psi_i}{\partial y} \frac{\partial \psi_j}{\partial y} + A_{44} \psi_i \psi_j \right) dx dy$$

$$F_i^1 = \int_{\Omega_e} q \psi_i dx dy + \oint_{\Gamma_e} Q_n \psi_i ds$$

$$F_i^2 = \oint_{\Gamma_e} \hat{M}_{nn} \psi_i ds, \quad F_i^3 = \oint_{\Gamma_e} \hat{M}_{ns} \psi_i ds$$





# Shear and Membrane Locking (Revisit)

## Shear Locking

Use reduced integration to evaluate all *shear* stiffnesses (i.e., all  $K_{ij}$  that contain transverse shear terms)

## Membrane Locking

Use reduced integration to evaluate all *membrane* stiffnesses (i.e., all  $K_{ij}$  that contain von Kármán nonlinear terms)

# NUMERICAL EXAMPLES

## Simply Supported Plate (SS2)

$$\bar{w} = w_0(0, 0) \frac{E_2 h^3}{a^4 q_0}, \quad \bar{\sigma}_{xx} = \sigma_{xx}(0, 0, \frac{h}{2}) \frac{h^2}{b^2 q_0}$$

$$\bar{\sigma}_{yy} = \sigma_{yy}(0, 0, \frac{h}{4}) \frac{h^2}{b^2 q_0}, \quad \bar{\sigma}_{xy} = \sigma_{xy}(\frac{a}{2}, \frac{b}{2}, -\frac{h}{2}) \frac{h^2}{b^2 q_0}$$

$$\bar{\sigma}_{xz} = \sigma_{xz}(\frac{a}{2}, 0, -\frac{h}{2}) \frac{h}{b q_0}, \quad \bar{\sigma}_{yz} = \sigma_{yz}(0, \frac{b}{2}, \frac{h}{2}) \frac{h}{b q_0}$$

$$\sigma_{xx}(A, A, \frac{h}{2}), \quad \sigma_{xy}(B, B, -\frac{h}{2}), \quad \sigma_{xz}(B, A, -\frac{h}{2})$$

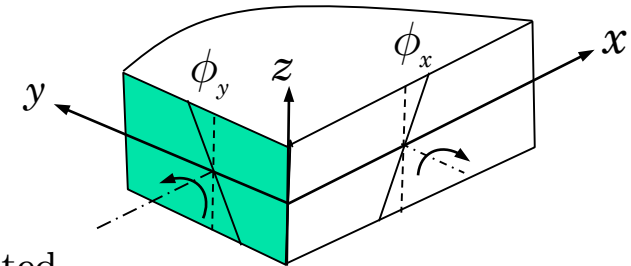
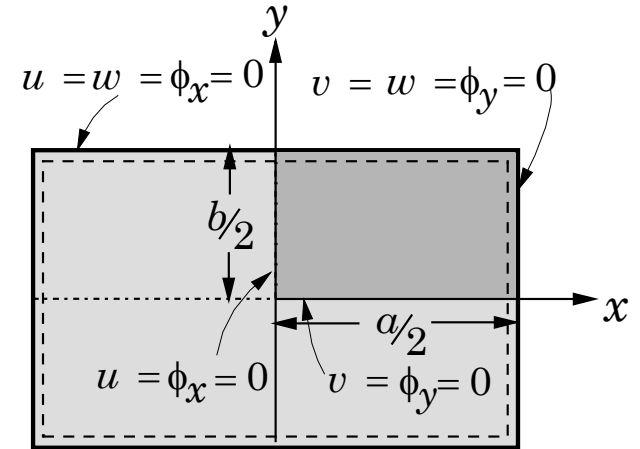


Table: The Gauss point locations at which the stresses are computed in the finite element analysis of simply supported plates.

Point	2L	4L	8L	1Q9	2Q9	4Q9
A	0.125a	0.0625a	0.0312a	0.1056a	0.0528a	0.0264a
B	0.375a	0.4375a	0.4687a	0.3943a	0.4472a	0.4736a

# Effect of Quadrature Rules and Shear Deformation on Deflection and Stresses

$a/h$	Mesh	$\bar{w} \times 10^2$	$\bar{\sigma}_{xx}$	$\bar{\sigma}_{xy}$	$\bar{\sigma}_{xz}$
Finite Element Solutions <sup>†</sup>					
10	2L-F	2.4742	0.1185	0.0727	0.2627
	2L-S	4.7120	0.2350	0.1446	0.2750
	2L-R	4.8887	0.2441	0.1504	0.2750
	1Q-F	4.5304	0.2294	0.1610	0.2813
	1Q-S	4.9426	0.2630	0.1639	0.2847
	1Q-R	4.9711	0.2645	0.1652	0.2886
	4L-F	3.8835	0.2160	0.1483	0.3366
	4L-S	4.7728	0.2661	0.1850	0.3356
	4L-R	4.8137	0.2684	0.1869	0.3356
	2Q-F	4.7707	0.2699	0.1930	0.3437
	2Q-S	4.7989	0.2715	0.1939	0.3424
	2Q-R	4.8005	0.2716	0.1943	0.3425
	8L-F	4.5268	0.2590	0.1891	0.3700
	8L-S	4.7966	0.2743	0.2743	0.2014
	8L-R	4.7866	0.2737	0.2737	0.2008
	4Q-F	4.7897	0.2749	0.2044	0.3737
	4Q-S	4.7916	0.2750	0.2043	0.3735
	4Q-R	4.7917	0.2750	0.2044	0.3735
Analytical Solutions					
	[15]	4.7914	0.2762	0.2085	0.3927

**Square plate under UDL**

**F – full integration**

**S – Selective integration**

**R- Reduced integration**

**L – Linear element**

**Q- Quadratic element**

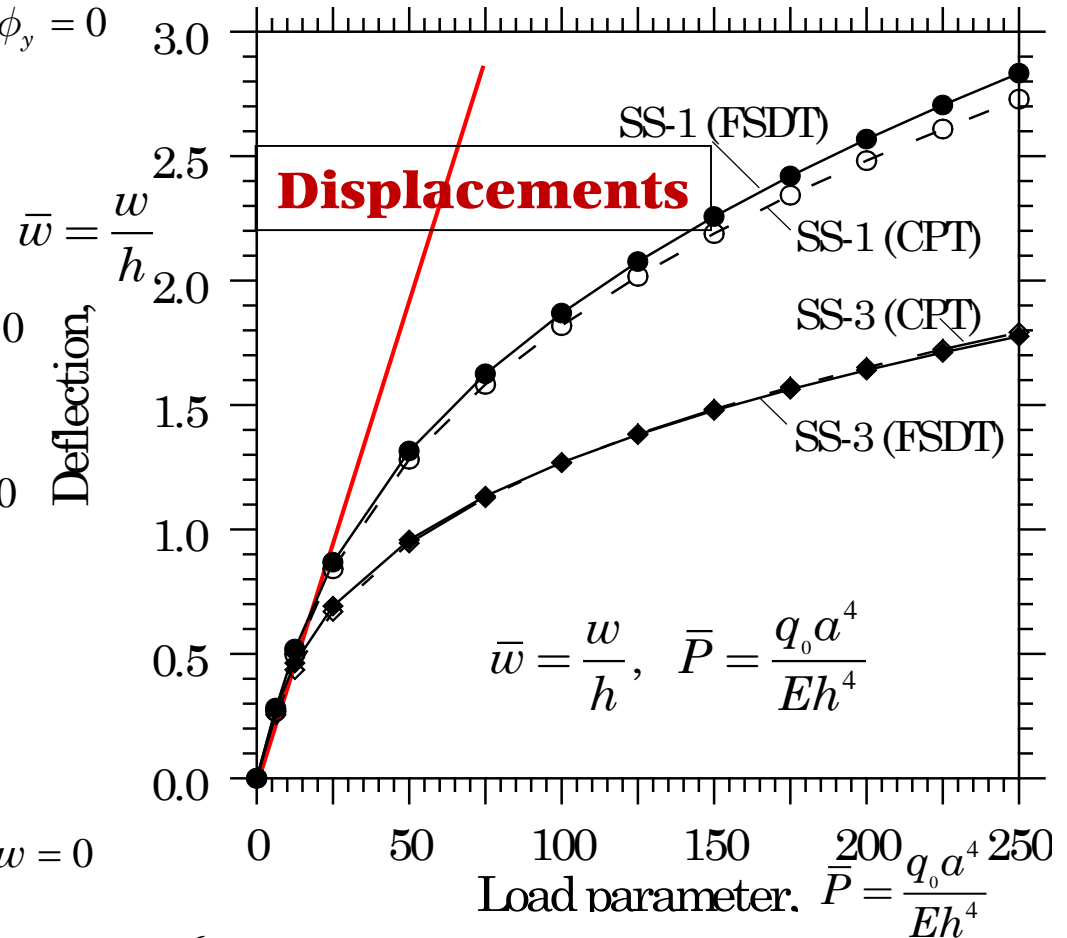
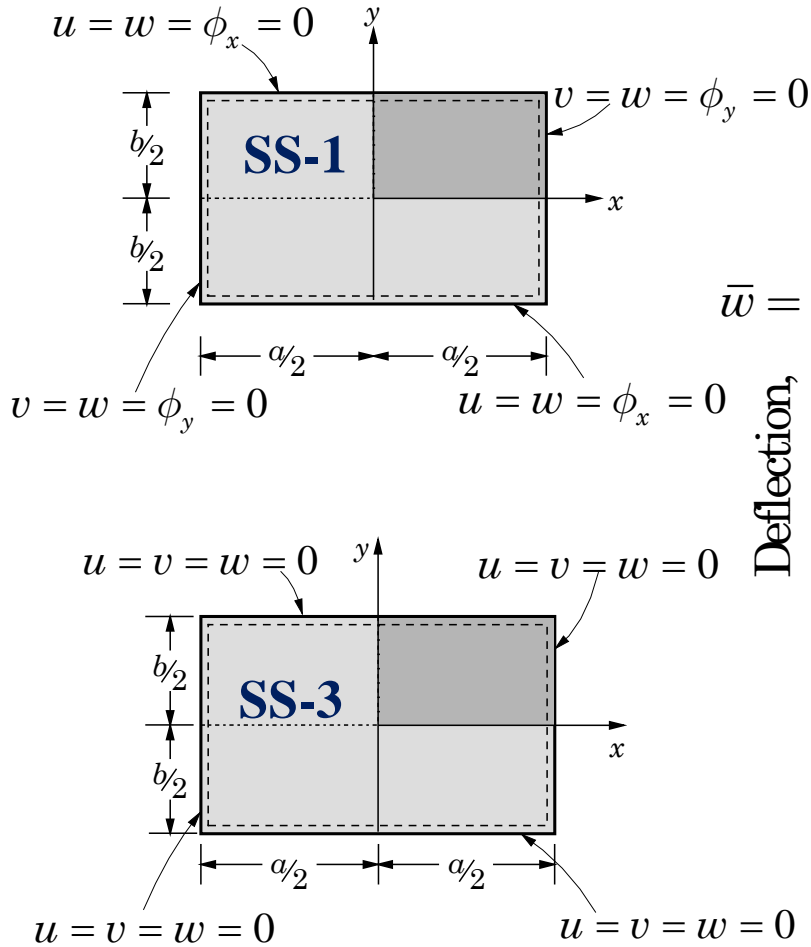


# Effect of Quadrature Rules and Shear Deformation on Deflection and Stresses

$a/h$	Mesh	$\bar{w} \times 10^2$	$\bar{\sigma}_{xx}$	$\bar{\sigma}_{xy}$	$\bar{\sigma}_{xz}$	
Finite Element Solutions						
100	2L-F	0.0469	0.0024	0.0014	0.2635	
	2L-S	4.4645	0.2350	0.1446	0.2750	
	2L-R	4.6412	0.2441	0.1504	0.2750	
	1Q-F	4.0028	0.2040	0.1591	0.2733	
	1Q-S	4.7196	0.2629	0.1643	0.2837	
	1Q-R	4.7483	0.2645	0.1652	0.2886	
	4L-F	0.1819	0.0108	0.0071	0.3462	
	4L-S	4.5481	0.2661	0.1850	0.3356	
	4L-R	4.5890	0.2684	0.1869	0.3356	
	2Q-F	4.4822	0.2644	0.1893	0.3485	
	2Q-S	4.5799	0.2715	0.1941	0.3414	
	2Q-R	4.5815	0.2716	0.1943	0.3425	
	8L-F	0.6497	0.0401	0.0275	0.3847	
	8L-S	4.5664	0.2737	0.2008	0.3691	
	8L-R	4.5764	0.2743	0.2014	0.3691	
	4Q-F	4.5530	0.2741	0.2020	0.3749	
	4Q-S	4.5728	0.2750	0.2044	0.3734	
	4Q-R	4.5729	0.2750	0.2044	0.3735	
	Analytical Solutions					
		[15]	4.5698	0.2762	0.2085	0.3927

# Bending of Simply Supported Plates

Isotropic plate under uniformly distributed transverse load



$a = b = 10$  in,  $h = 1$  in,  $E = 7.8 \times 10^6$  psi,  $\nu = 0.3$

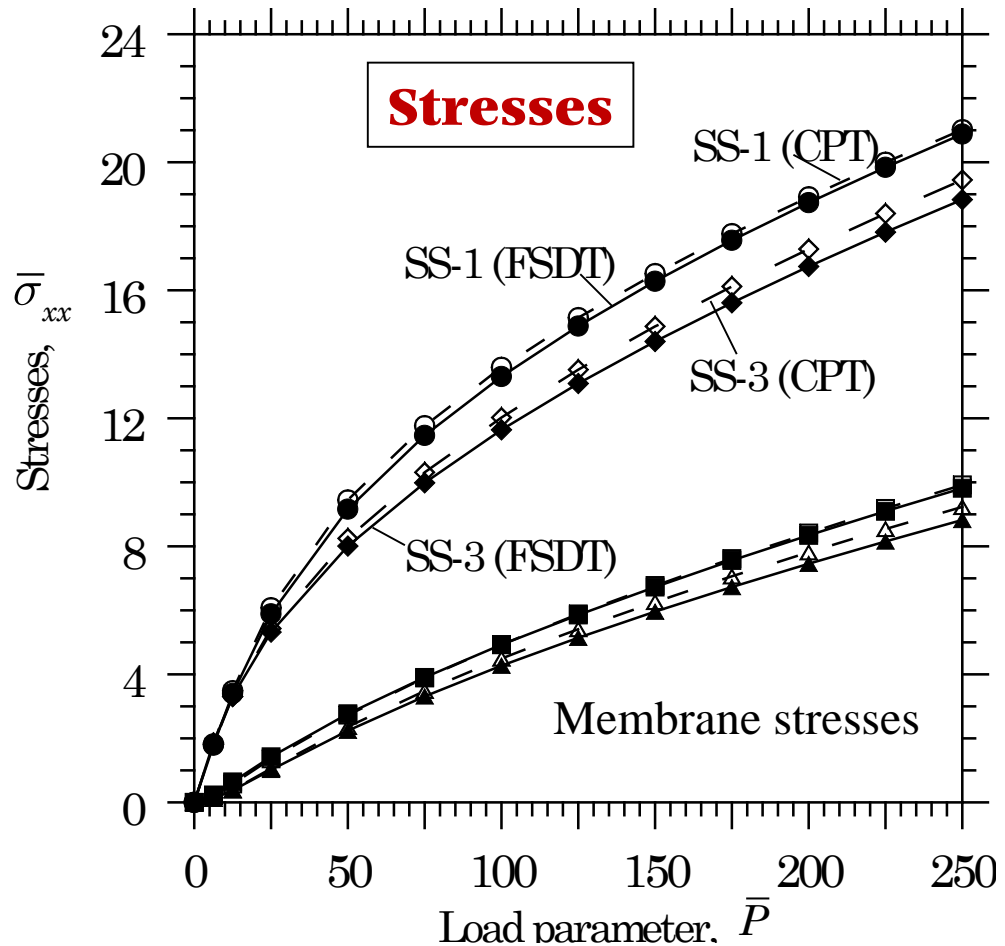
# Bending of Simply Supported Plates

Isotropic plate under uniformly distributed transverse load

$$\bar{\sigma}_{xx} = \sigma_{xx} \left( \frac{a^2}{Eh^2} \right), \quad \bar{P} = \frac{q_0 a^4}{Eh^4}$$

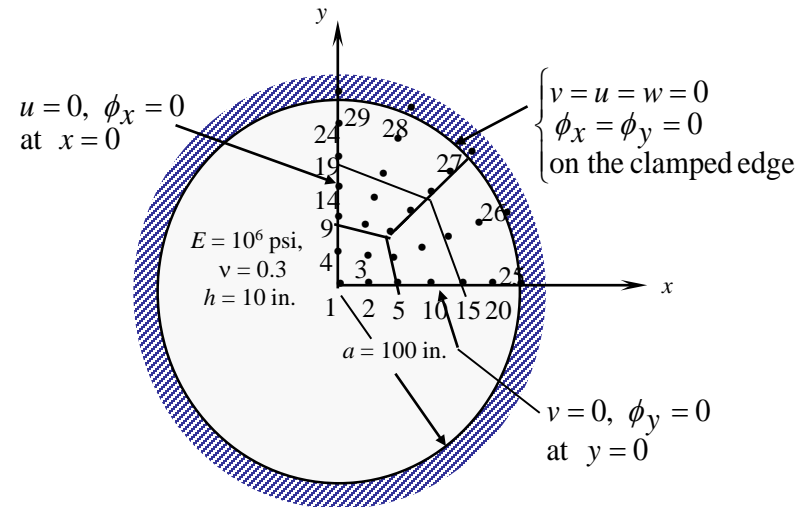
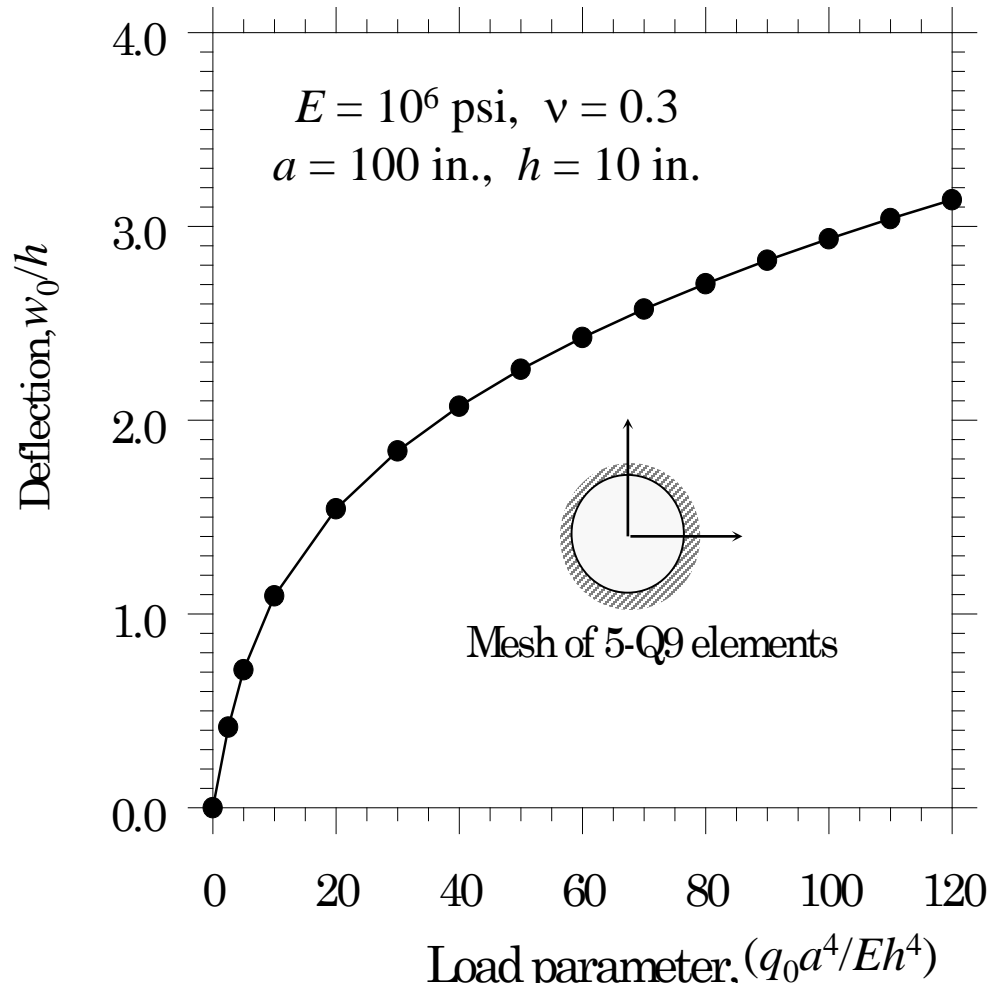
$$a = b = 10 \text{ in}, \quad h = 1 \text{ in},$$

$$E = 7.8 \times 10^6 \text{ psi}, \quad \nu = 0.3$$

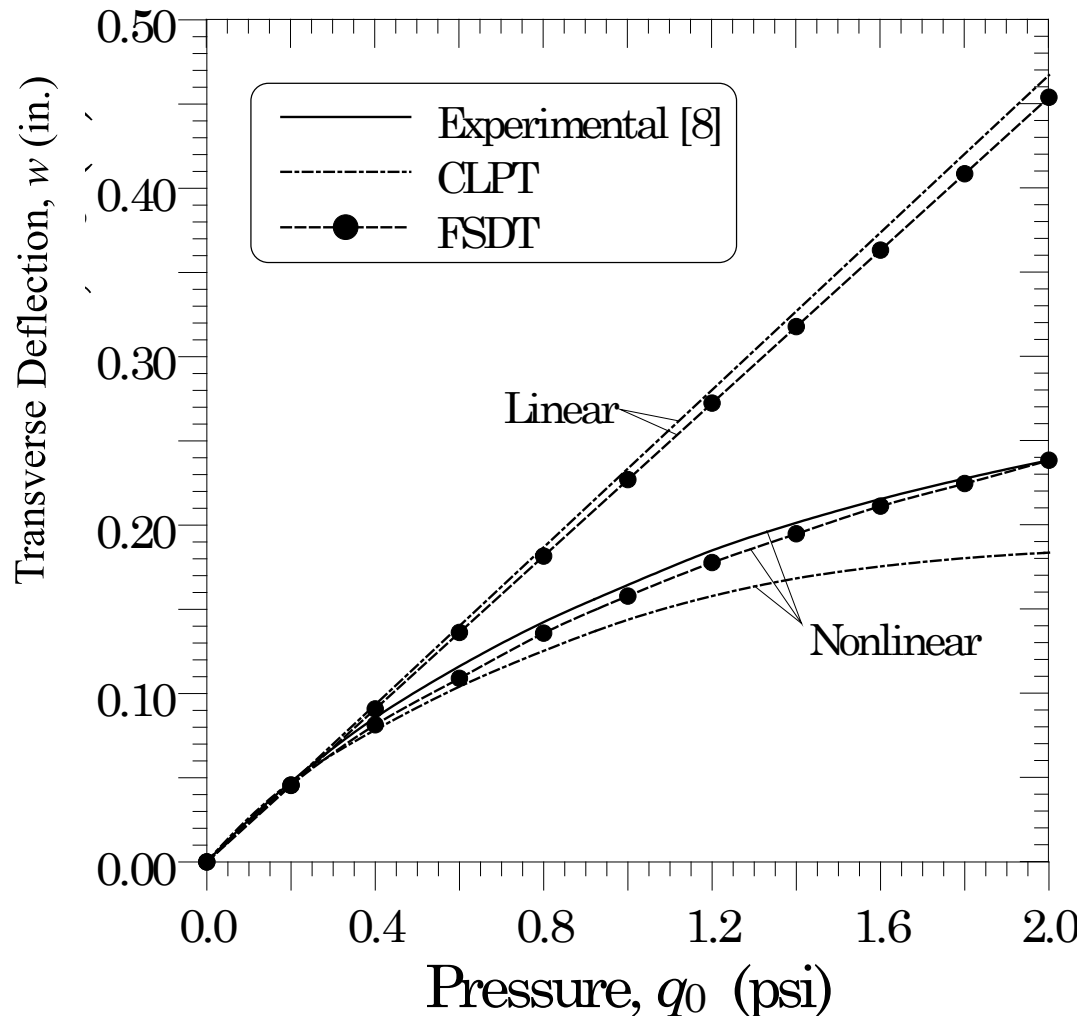




# Clamped Circular Plate under UDL



# Simply Supported (SS2) Orthotropic\* Plate



Geometry and Material Properties

$$a = b = 12 \text{ in}, h = 0.138 \text{ in}$$

$$E_1 = 3 \times 10^6 \text{ psi}, E_2 = 1.28 \times 10^6 \text{ psi}$$

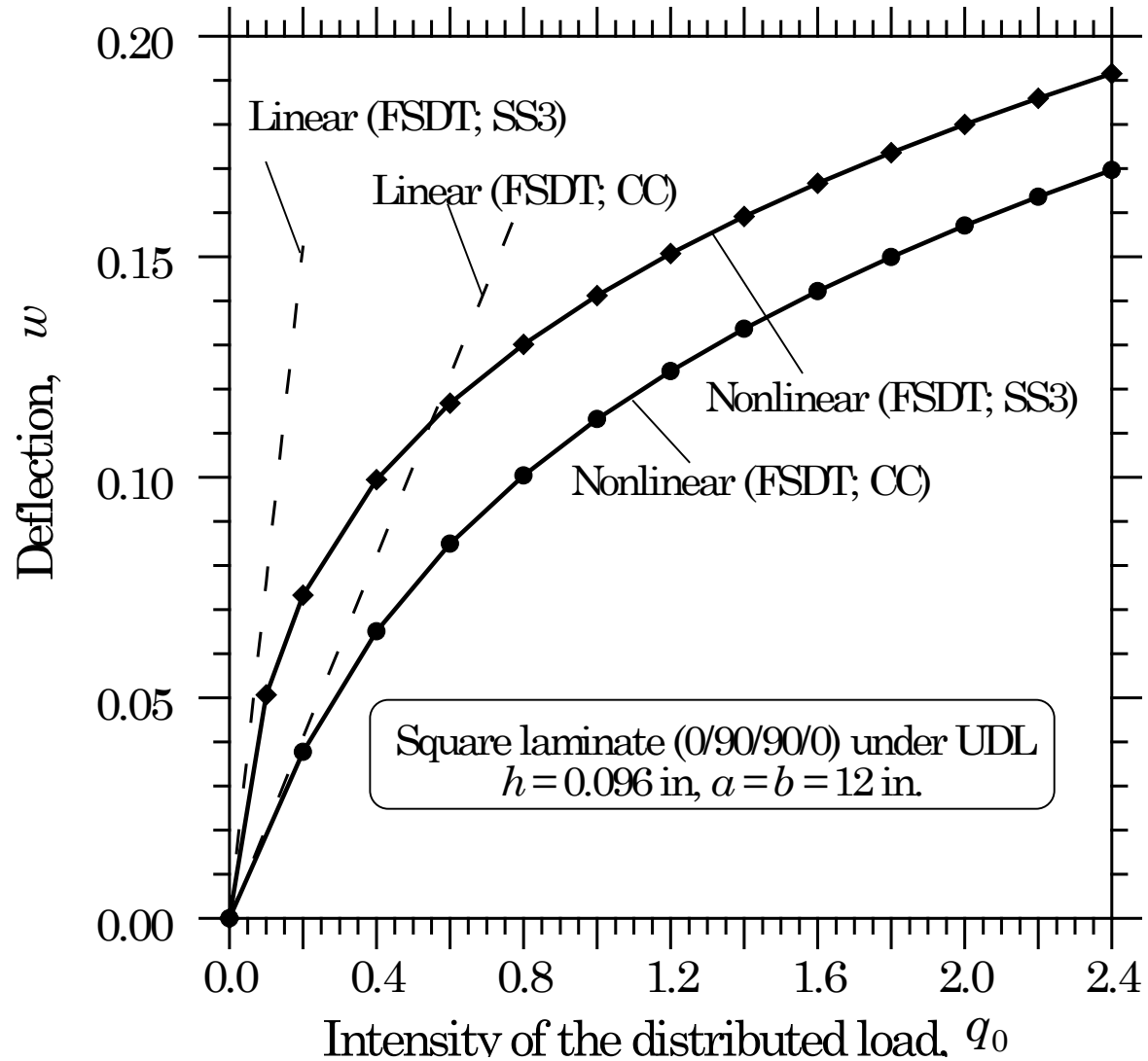
$$G_{12} = G_{23} = G_{13} = 0.37 \times 10^6 \text{ psi}$$

$$\nu_{12} = \nu_{23} = \nu_{13} = 0.32$$

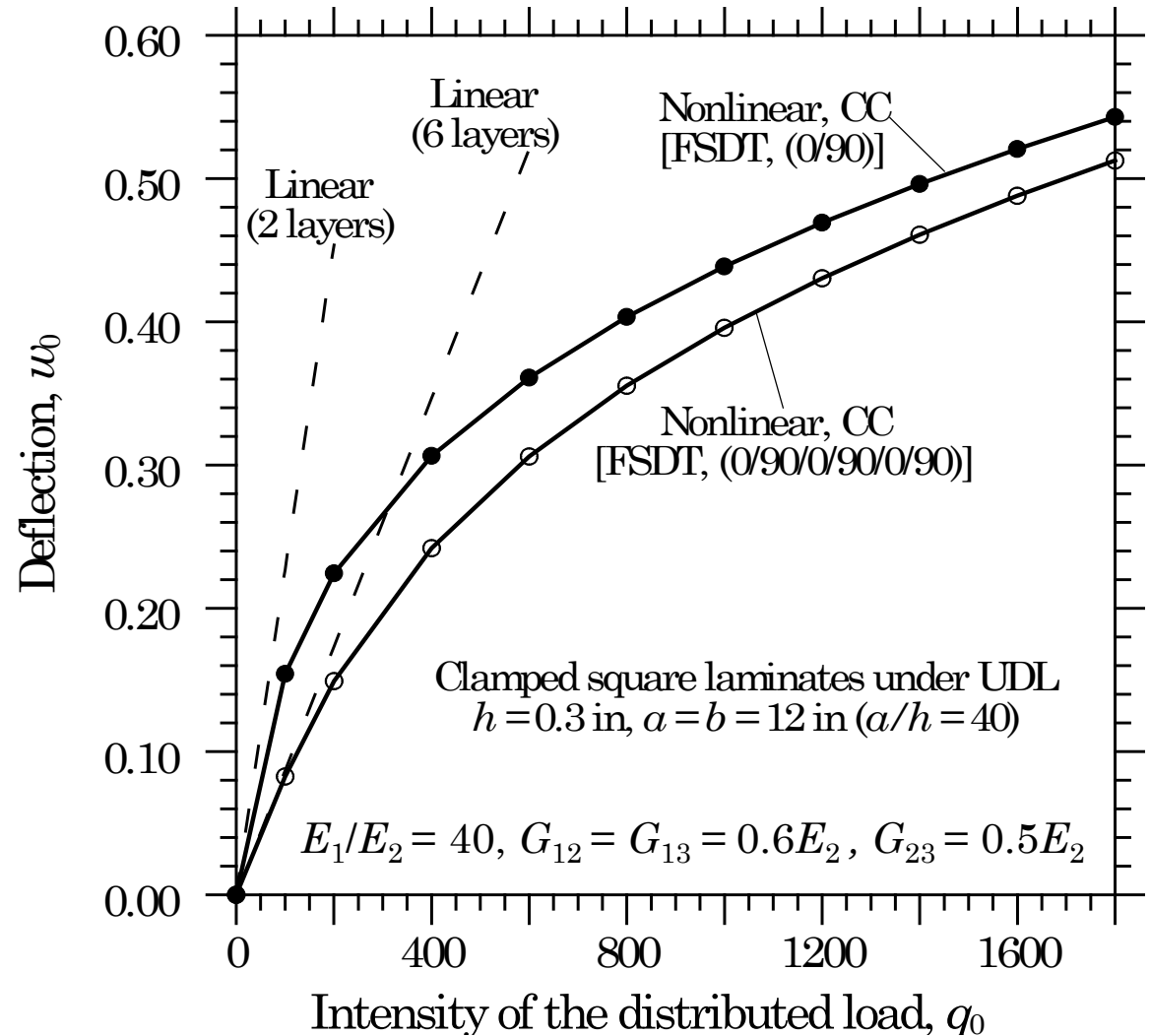
[8] Zaghoul, S. A. and Kennedy, J. B., "Nonlinear Behavior of Symmetrically Laminated Plates," *Journal of Applied Mechanics*, 42, 234-236, 1975.

# DEFLECTION VS. LOAD PARAMETER FOR (0/90/90/0) LAMINATE UDL

$$\begin{aligned}
 E_1 &= 1.8282 \times 10^6 \text{ psi,} \\
 E_2 &= 1.8315 \times 10^6 \text{ psi,} \\
 G_{12} &= G_{13} = G_{23} \\
 &= 0.3125 \times 10^6 \text{ psi,} \\
 \nu_{12} &= 0.2395
 \end{aligned}$$



# DEFLECTION VS. LOAD PARAMETER FOR TWO- AND SIX-LAYER CROSS-PLY LAMINATES UDL





# SUMMARY

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In this lecture we have covered the following topics:

- Governing equations of FSDT
- Finite element models of FSDT
- Shear and membrane locking
- Numerical examples