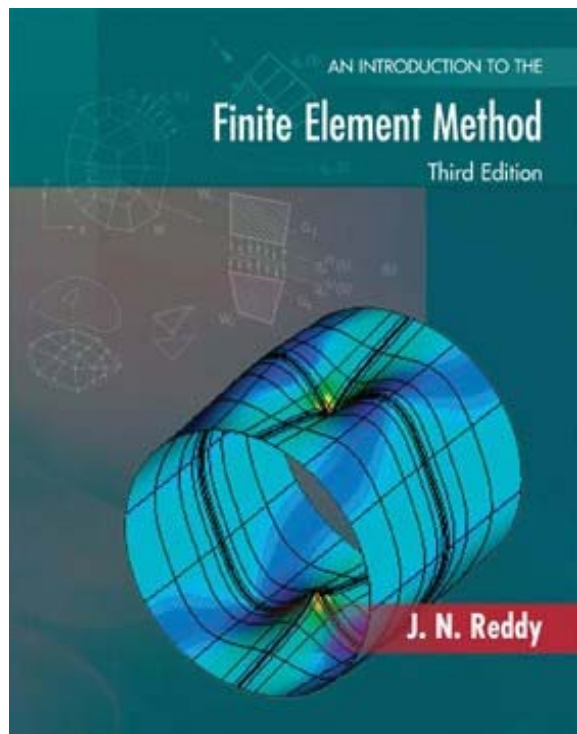


# The Finite Element Method

## Plane Elasticity

**Read: Chapter 11**



**JN Reddy**

### CONTENTS

- Governing equations
- Weak form formulation
- Finite element models using the weak form
- Triangular and rectangular elements
- Shear locking
- Modeling aspects and discussion

**Plane Elasticity : 1**

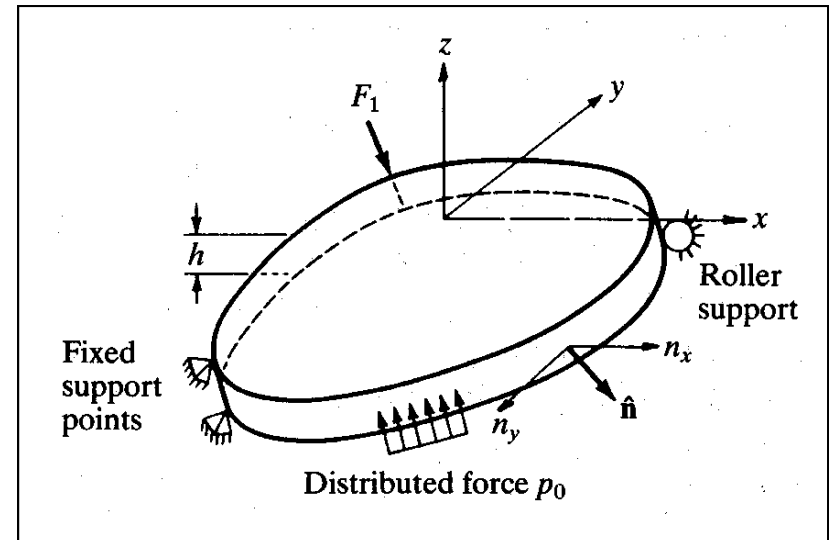
# REVIEW OF PLANE ELASTICITY

## Plane Stress Problems

$$\sigma_{xx} = \sigma_{xx}(x, y, t), \quad \sigma_{yy} = \sigma_{yy}(x, y, t),$$

$$\sigma_{xy} = \sigma_{xy}(x, y, t),$$

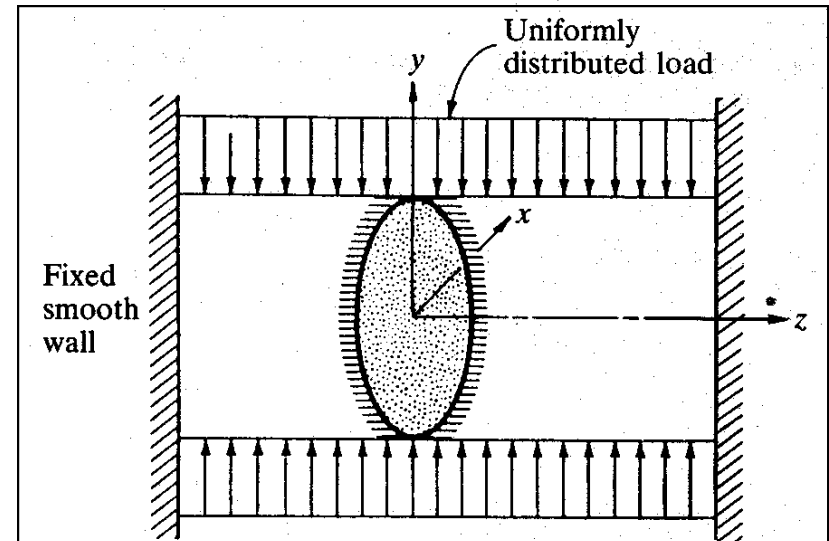
$$\sigma_{xz} = 0, \quad \sigma_{yz} = 0, \quad \sigma_{zz} = 0$$



## Plane Strain Problems

$$u = u(x, y, t), \quad v = v(x, y, t), \quad w = 0$$

$$\Rightarrow \varepsilon_{xz} = 0, \quad \varepsilon_{yz} = 0, \quad \varepsilon_{zz} = 0$$



# GOVERNING EQUATIONS

## Stress equations of motion

$$\frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \sigma_{xy}}{\partial y} + f_x = \rho \frac{\partial^2 u_x}{\partial t^2}$$

$$\frac{\partial \sigma_{xy}}{\partial x} + \frac{\partial \sigma_{yy}}{\partial y} + f_y = \rho \frac{\partial^2 u_y}{\partial t^2}$$

## Stress-strain relations (orthotropic)

$$\begin{Bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{xy} \end{Bmatrix} = \begin{bmatrix} C_{11} & C_{12} & 0 \\ C_{12} & C_{22} & 0 \\ 0 & 0 & C_{66} \end{bmatrix} \begin{Bmatrix} \epsilon_{xx} \\ \epsilon_{yy} \\ 2\epsilon_{xy} \end{Bmatrix}$$

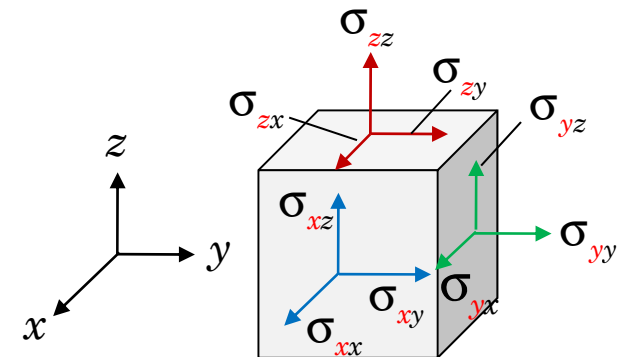
## Cauchy's formula

$$t_x = \sigma_{xx} n_x + \sigma_{xy} n_y$$

$$t_y = \sigma_{xy} n_x + \sigma_{yy} n_y$$

## Strain-displacement relations

$$\epsilon_{xx} = \frac{\partial u}{\partial x}, \quad \epsilon_{yy} = \frac{\partial v}{\partial y}, \quad 2\epsilon_{xy} = \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x}$$





## GOVERNING EQUATIONS (continued)

### Plane-strain constitutive relations

$$C_{11} = \frac{E_1(1 - \nu_{12}\nu_{21})}{(1 + \nu_{12})(1 - \nu_{12} - 2\nu_{12}\nu_{21})}, \quad C_{22} = \frac{E_2(1 - \nu_{12}\nu_{21})}{(1 + \nu_{12})(1 - \nu_{12} - 2\nu_{12}\nu_{21})}$$

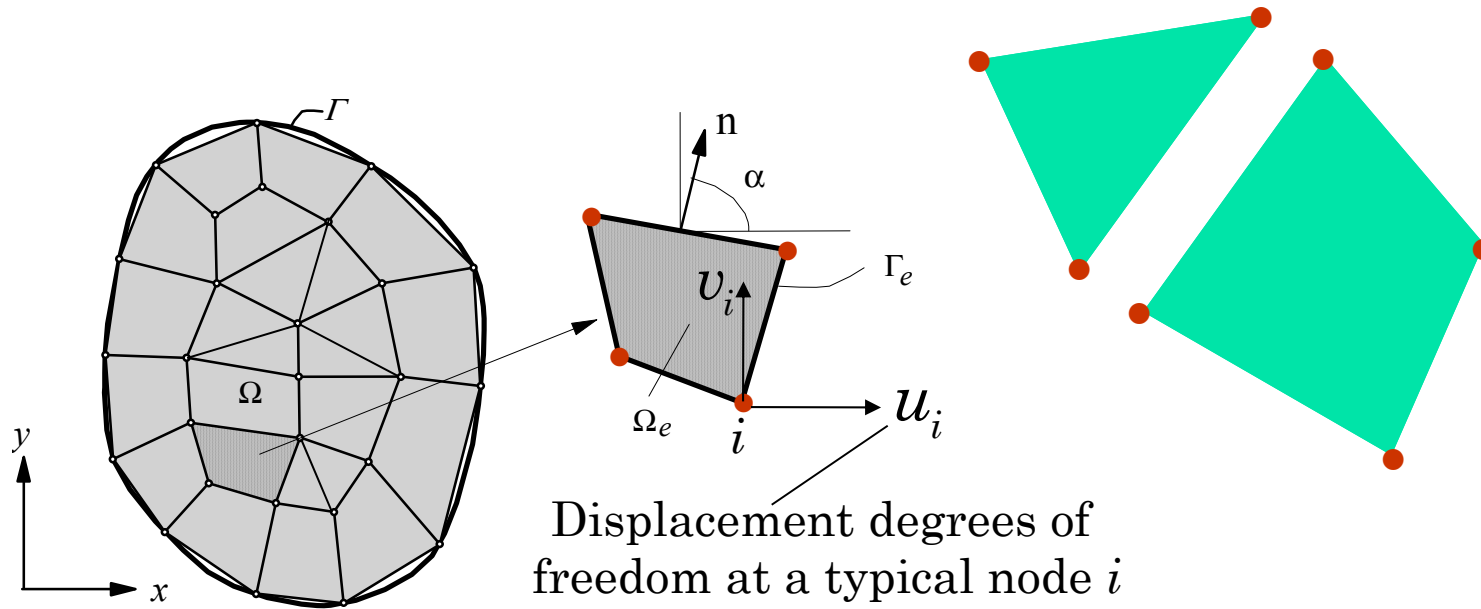
$$C_{12} = \frac{\nu_{12}E_2}{(1 - \nu_{12} - 2\nu_{12}\nu_{21})}, \quad C_{66} = G_{12}, \quad \nu_{12}E_2 = \nu_{21}E_1$$

### Plane-stress constitutive relations

$$C_{11} = \frac{E_1}{(1 - \nu_{12}\nu_{21})}, \quad C_{22} = \frac{E_2}{(1 - \nu_{12}\nu_{21})}, \quad C_{12} = \frac{\nu_{12}E_2}{(1 - \nu_{12}\nu_{21})}$$

$$C_{66} = G_{12}, \quad \nu_{12}E_2 = \nu_{21}E_1$$

# DOMAIN DISCRETIZATION (MESH)



# Weak Forms of the Equations

$$\begin{aligned}
 0 &= h_e \int_{\Omega^e} w_1 \left( \rho \ddot{u} - \frac{\partial \sigma_{xx}}{\partial x} - \frac{\partial \sigma_{xy}}{\partial y} - f_x \right) dA \\
 &= h_e \int_{\Omega^e} \left( \rho w_1 \ddot{u} + \frac{\partial w_1}{\partial x} \sigma_{xx} + \frac{\partial w_1}{\partial y} \sigma_{xy} - w_1 f_x \right) dA \\
 &\quad - h_e \oint_{S^e} w_1 t_x dS
 \end{aligned}$$

$$\begin{aligned}
 0 &= h_e \int_{\Omega^e} w_2 \left( \rho \ddot{v} - \frac{\partial \sigma_{xy}}{\partial x} - \frac{\partial \sigma_{yy}}{\partial y} - f_y \right) dA \\
 &= h_e \int_{\Omega^e} \left( \rho w_2 \ddot{v} + \frac{\partial w_2}{\partial x} \sigma_{xy} + \frac{\partial w_2}{\partial y} \sigma_{yy} - w_2 f_y \right) dA \\
 &\quad - h_e \oint_{S^e} w_2 t_y dS
 \end{aligned}$$

$$\begin{aligned}
 \sigma_{xx} &= c_{11} \frac{\partial u}{\partial x} + c_{12} \frac{\partial v}{\partial y} \\
 \sigma_{yy} &= c_{12} \frac{\partial u}{\partial x} + c_{22} \frac{\partial v}{\partial y} \\
 \sigma_{xy} &= c_{66} \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right)
 \end{aligned}$$

$$t_x = (\sigma_{xx} n_x + \sigma_{xy} n_y), \quad t_y = (\sigma_{xy} n_x + \sigma_{yy} n_y)$$

$$w_1 \sim \delta u, \quad w_2 \sim \delta v$$



# FINITE ELEMENT MODEL

## using weak form

### Finite element approximation

$$u \approx \sum_{j=1}^n u_j^e(t) \psi_j^e(x, y), \quad v \approx \sum_{j=1}^n v_j^e(t) \psi_j^e(x, y)$$

### Finite element model

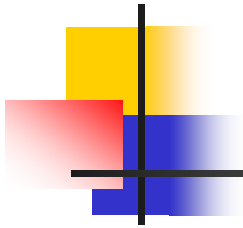
$$\begin{bmatrix} [M^{11}] & [0] \\ [0] & [M^{22}] \end{bmatrix} \begin{Bmatrix} \{\ddot{u}\} \\ \{\ddot{v}\} \end{Bmatrix} + \begin{bmatrix} [K^{11}] & [K^{12}] \\ [K^{21}] & [K^{22}] \end{bmatrix} \begin{Bmatrix} \{u\} \\ \{v\} \end{Bmatrix} = \begin{Bmatrix} \{F^1\} \\ \{F^2\} \end{Bmatrix}$$

$$[\mathbf{M}] \{\ddot{\Delta}\} + [\mathbf{K}] \{\Delta\} = \{\mathbf{F}\}$$

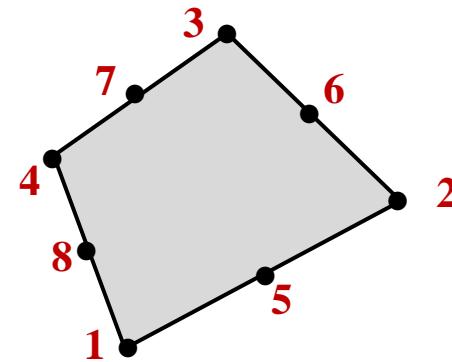
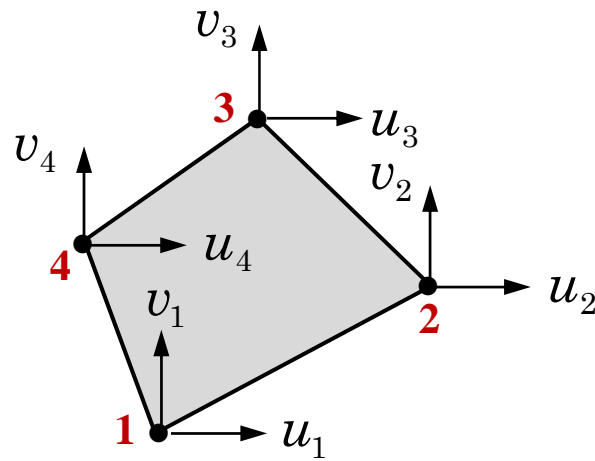
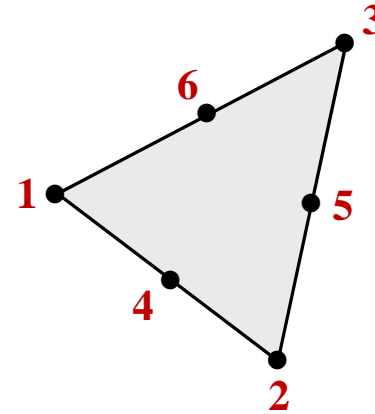
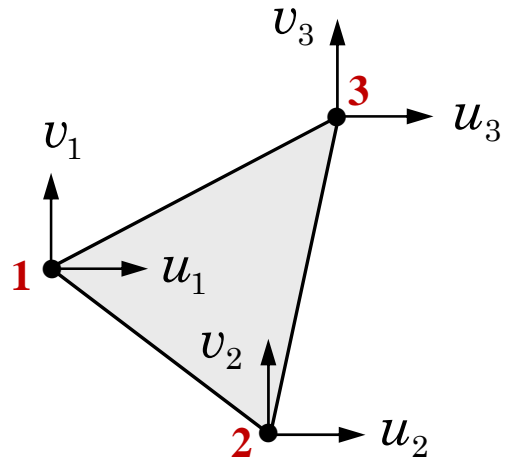
$$K_{ij}^{11} = h_e \int_{\Omega^e} \left( c_{11} \frac{\partial \psi_i}{\partial x} \frac{\partial \psi_j}{\partial x} + c_{66} \frac{\partial \psi_i}{\partial y} \frac{\partial \psi_j}{\partial y} \right) dA \quad F_i^1 = h_e \int_{\Omega^e} \psi_i f_x dA + h_e \oint_{S^e} \psi_i t_x dS$$

$$K_{ij}^{12} = K_{ji}^{21} = h_e \int_{\Omega^e} \left( c_{12} \frac{\partial \psi_i}{\partial x} \frac{\partial \psi_j}{\partial y} + c_{66} \frac{\partial \psi_i}{\partial y} \frac{\partial \psi_j}{\partial x} \right) dA \quad F_i^2 = h_e \int_{\Omega^e} \psi_i f_y dx dy + h_e \oint_{S^e} \psi_i t_y dS$$

$$K_{ij}^{22} = h_e \int_{\Omega^e} \left( c_{66} \frac{\partial \psi_i}{\partial x} \frac{\partial \psi_j}{\partial x} + c_{22} \frac{\partial \psi_i}{\partial y} \frac{\partial \psi_j}{\partial y} \right) dA$$



# FINITE ELEMENTS







# Numerical Values of Typical Element Matrices

$$K_{ij}^{11} = h_e \int_{\Omega^e} \left( c_{11} \frac{\partial \psi_i}{\partial x} \frac{\partial \psi_j}{\partial x} + c_{66} \frac{\partial \psi_i}{\partial y} \frac{\partial \psi_j}{\partial y} \right) dA$$

$$[K^{11}] = \frac{c_{11} h}{6a} \begin{bmatrix} 2b & -2b & -b & b \\ -2b & 2b & b & -b \\ -b & b & 2b & -2b \\ b & -b & -2b & 2b \end{bmatrix} + \frac{c_{66} h}{6b} \begin{bmatrix} 2a & -2a & -a & a \\ -2a & 2a & a & -a \\ -a & a & 2a & -2a \\ a & -a & -2a & 2a \end{bmatrix}$$

$$K_{ij}^{22} = h_e \int_{\Omega^e} \left( c_{66} \frac{\partial \psi_i}{\partial x} \frac{\partial \psi_j}{\partial x} + c_{22} \frac{\partial \psi_i}{\partial y} \frac{\partial \psi_j}{\partial y} \right) dA$$

$$[K^{22}] = \frac{c_{66} h}{6a} \begin{bmatrix} 2b & -2b & -b & b \\ -2b & 2b & b & -b \\ -b & b & 2b & -2b \\ b & -b & -2b & 2b \end{bmatrix} + \frac{c_{22} h}{6b} \begin{bmatrix} 2a & -2a & -a & a \\ -2a & 2a & a & -a \\ -a & a & 2a & -2a \\ a & -a & -2a & 2a \end{bmatrix}$$



# Eigenvalue Problems

$$\mathbf{M}\ddot{\Delta} + \mathbf{K}\Delta = \mathbf{F}$$

**Assume periodic solution**

$$\Delta = \Delta_0 e^{i\omega t}$$

$$\left(-\lambda\mathbf{M}^e + \mathbf{K}^e\right)\Delta_0^e = \mathbf{Q}_0^e, \quad \lambda = \omega^2$$

**Assembled equations**

$$\left(-\lambda\mathbf{M} + \mathbf{K}\right)\mathbf{U}_0 = \mathbf{Q}_0, \quad \lambda = \omega^2$$



# TIME APPROXIMATIONS

## Semidiscrete FE model

$$\mathbf{M}^e \ddot{\Delta}^e + \mathbf{K}^e \Delta^e = \mathbf{F}^e$$

## Newmark scheme (second-order equations)

$$\begin{aligned}\Delta^{s+1} &= \Delta^s + \delta t \dot{\Delta}^s + \frac{1}{2} (\delta t)^2 \ddot{\Delta}^{s,\gamma} \\ \dot{\Delta}^{s+1} &= \dot{\Delta}^s + \delta t \ddot{\Delta}^{s,\alpha}, \quad \ddot{\Delta}^{s,\alpha} = (1 - \alpha) \ddot{\Delta}^s + \alpha \ddot{\Delta}^{s+1}\end{aligned}$$

## Fully discretized model

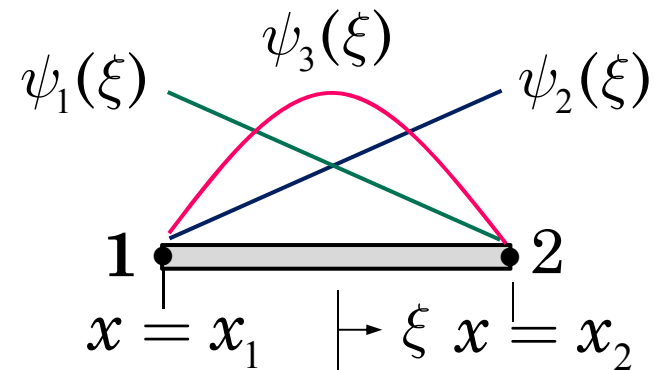
$$\hat{\mathbf{K}}^{s+1} \Delta^{s+1} = \hat{\mathbf{F}}^{s+1}, \quad \hat{\mathbf{K}}^{s+1} = \mathbf{K}^{s+1} + a_3 \mathbf{M}^{s+1}$$

$$\hat{\mathbf{F}}^{s+1} = \mathbf{F}^{s+1} + \mathbf{M}^{s+1} \left( a_3 \Delta^s + a_4 \dot{\Delta}^s + a_5 \ddot{\Delta}^s \right)$$

# Static Condensation Procedure

$$\begin{aligned}\psi_1(\xi) &= \frac{1}{2}(1 - \xi) \\ \psi_2(\xi) &= \frac{1}{2}(1 + \xi) \\ \psi_3(\xi) &= 1 - \xi^2\end{aligned}$$

$$\begin{aligned}x &= x_1\psi_1(\xi) + x_2\psi_2(\xi) \\ &= \frac{x_1 + x_2}{2} + \frac{x_2 - x_1}{2}\xi\end{aligned}$$



$$u(x) = u_1\psi_1(\xi) + u_2\psi_2(\xi) + \alpha\psi_3(\xi)$$

$$0 = \int_{x_1}^{x_2} \left( EA \frac{d\delta u}{dx} \frac{du}{dx} - f\delta u \right) dx - \delta u(x_1)P_1 - \delta u(x_2)P_2$$

$$\begin{bmatrix} K_{11} & K_{12} & K_{13} \\ K_{21} & K_{22} & K_{23} \\ K_{31} & K_{32} & K_{33} \end{bmatrix} \begin{Bmatrix} u_1 \\ u_2 \\ \alpha \end{Bmatrix} = \begin{Bmatrix} f_1 \\ f_2 \\ f_3 \end{Bmatrix} + \begin{Bmatrix} P_1 \\ P_2 \\ 0 \end{Bmatrix}$$



# Static Condensation Procedure

$$\begin{bmatrix} K_{11} & K_{12} & K_{13} \\ K_{21} & K_{22} & K_{23} \\ K_{31} & K_{32} & K_{33} \end{bmatrix} \begin{Bmatrix} u_1 \\ u_2 \\ \alpha \end{Bmatrix} = \begin{Bmatrix} f_1 \\ f_2 \\ f_3 \end{Bmatrix} + \begin{Bmatrix} P_1 \\ P_2 \\ 0 \end{Bmatrix}$$

$$K_{33}\alpha = f_3 - K_{31}u_1 - K_{32}u_2 \Rightarrow \alpha = (K_{33})^{-1} (f_3 - K_{31}u_1 - K_{32}u_2)$$

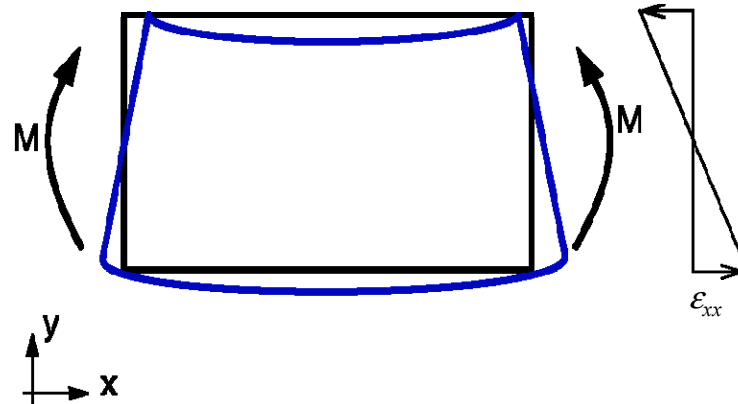
$$\begin{bmatrix} \mathbf{K}_{uu} & \mathbf{K}_{u\alpha} \\ \mathbf{K}_{\alpha u} & K_{\alpha\alpha} \end{bmatrix} \begin{Bmatrix} \mathbf{u} \\ \alpha \end{Bmatrix} = \begin{Bmatrix} \mathbf{F}_u \\ f_3 \end{Bmatrix}, \quad \alpha = (K_{\alpha\alpha})^{-1} (f_3 - \mathbf{K}_{\alpha u} \mathbf{u})$$

$$\mathbf{K}_{uu} \mathbf{u} + \mathbf{K}_{u\alpha} \alpha = \mathbf{F}_u \Rightarrow \mathbf{K}_{uu} \mathbf{u} + \mathbf{K}_{u\alpha} (K_{\alpha\alpha})^{-1} (f_3 - \mathbf{K}_{\alpha u} \mathbf{u}) = \mathbf{F}_u$$

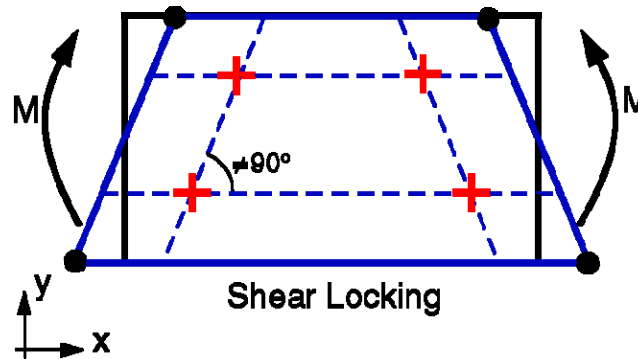
$$\left[ \mathbf{K}_{uu} - \mathbf{K}_{u\alpha} (K_{\alpha\alpha})^{-1} \mathbf{K}_{\alpha u} \right] \mathbf{u} = \mathbf{F}_u - \mathbf{K}_{u\alpha} (K_{\alpha\alpha})^{-1} f_3 \text{ or } \hat{\mathbf{K}}_{uu} \mathbf{u} = \hat{\mathbf{F}}_u$$

# BEHAVIOR OF THE LINEAR PLANE ELASTICITY ELEMENT

**Pure bending deformation**



**Linear element Deformation (incorrect)**





# Elimination of Shear Locking in Linear Elements

**Basic idea:** Start with the standard expansion in terms of bilinear shape functions for a typical linear quadrilateral element, quadratic modes are added as follows:

$$\mathbf{u}_h(\xi, \eta) = \sum_{j=1}^4 \psi_j(\xi, \eta) \Delta_j^e + \sum_{i=5}^6 \psi_i(\xi, \eta) \boldsymbol{\alpha}_i^e$$

where  $\psi_i$  ( $i=1,2,3,4$ ) are the standard bilinear interpolation functions and

$$\psi_5(\xi, \eta) = 1 - \xi^2, \quad \psi_6(\xi, \eta) = 1 - \eta^2$$

are the incompatible modes;  $\boldsymbol{\alpha}_i^e$  ( $i=5,6$ ) are generalized displacements (node-less variables).

The generalized displacements associated with the incompatible modes are unique to each element and must be eliminated via “static condensation”.



# Elimination of Shear Locking in Linear Elements (continued)

We begin with the standard definition of the stiffness matrix:

$$\mathbf{K} = \int_{\Omega^e} \mathbf{B}^T \mathbf{C} \mathbf{B} \, d\mathbf{x}$$

where  $\mathbf{B} = [\mathbf{B}_1 \quad \mathbf{B}_2 \quad \mathbf{B}_3 \quad \mathbf{B}_4 \quad | \quad \mathbf{B}_5 \quad \mathbf{B}_6]$  and  $\boldsymbol{\alpha} = \begin{Bmatrix} \alpha_5 \\ \alpha_6 \end{Bmatrix}$

$$\begin{bmatrix} \mathbf{K}^{\Delta\Delta} & \mathbf{K}^{\Delta\alpha} \\ \mathbf{K}^{\alpha\Delta} & \mathbf{K}^{\alpha\alpha} \end{bmatrix} \begin{Bmatrix} \Delta \\ \alpha \end{Bmatrix} = \begin{Bmatrix} \mathbf{F} \\ \mathbf{0} \end{Bmatrix} \quad \text{or} \quad \mathbf{K}^{\Delta\Delta} \Delta + \mathbf{K}^{\Delta\alpha} \alpha = \mathbf{F}, \quad \mathbf{K}^{\alpha\Delta} \Delta + \mathbf{K}^{\alpha\alpha} \alpha = 0$$

**Static condensation:** Solving the second equation for  $\alpha$ , we obtain

$$\alpha = -(\mathbf{K}^{\alpha\alpha})^{-1} \mathbf{K}^{\alpha\Delta} \Delta$$

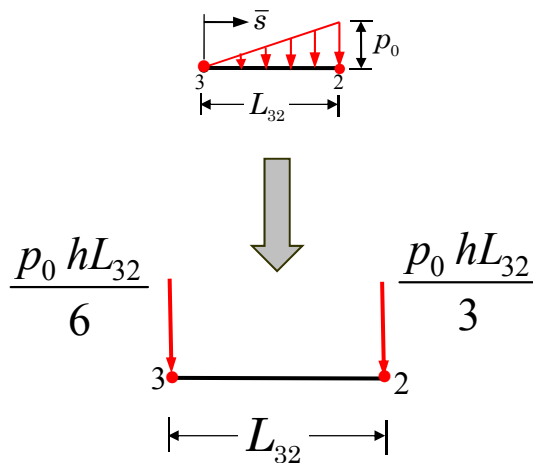
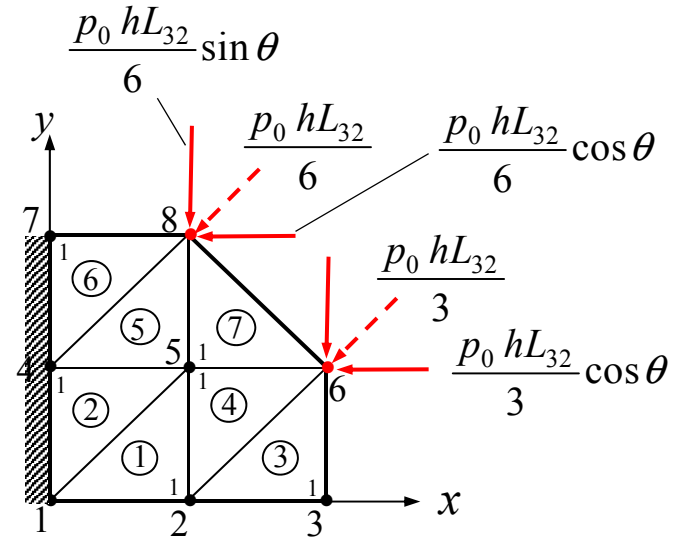
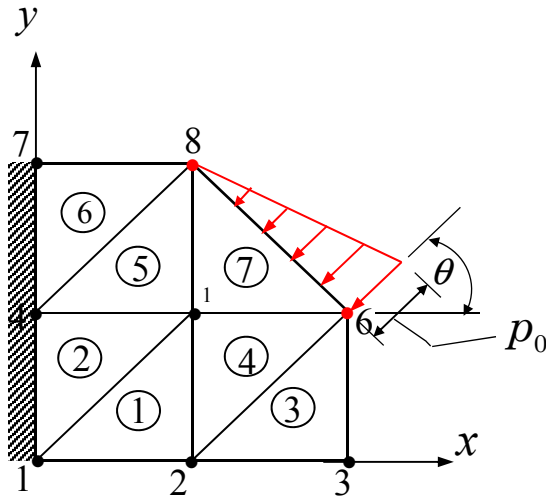
Substituting into the first equation, we arrive at

$$\hat{\mathbf{K}} \Delta = \mathbf{F} \quad \text{where} \quad \hat{\mathbf{K}} = \mathbf{K}^{\Delta\Delta} - \mathbf{K}^{\Delta\alpha} (\mathbf{K}^{\alpha\alpha})^{-1} \mathbf{K}^{\alpha\Delta}$$



# MODELING ASPECTS:

## Load Calculation



$$F_8^x = -\frac{p_0 h L_{32}}{6} \cos \theta \Rightarrow F_{15} = -\frac{p_0 h L_{32}}{6} \cos \theta$$

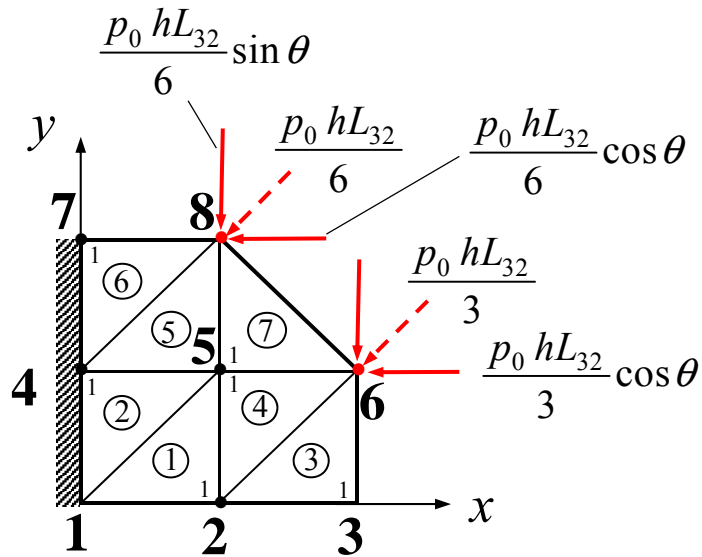
$$F_8^y = -\frac{p_0 h L_{32}}{6} \sin \theta \Rightarrow F_{16} = -\frac{p_0 h L_{32}}{6} \sin \theta$$

$$F_6^x = -\frac{p_0 h L_{32}}{3} \cos \theta \Rightarrow F_{11} = -\frac{p_0 h L_{32}}{3} \cos \theta$$

$$F_6^y = -\frac{p_0 h L_{32}}{3} \sin \theta \Rightarrow F_{12} = -\frac{p_0 h L_{32}}{3} \sin \theta$$

# MODELING ASPECTS:

## Assembly of Element coefficients

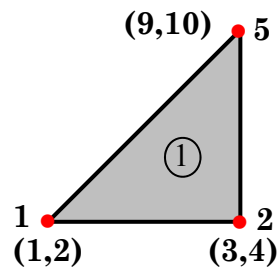


$$K_{11} = K_{55}^1 + K_{33}^2, \quad K_{12} = K_{56}^1 + K_{34}^2$$

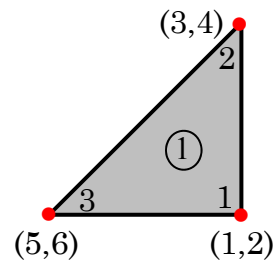
$$K_{13} = K_{51}^1, \quad K_{15} = 0, \quad K_{23} = K_{61}^1$$

$$K_{19} = K_{53}^1 + K_{35}^2, \quad K_{88} = K_{22}^2 + K_{66}^5 + K_{44}^6$$

$$K_{77} = K_{11}^2 + K_{55}^5 + K_{33}^6, \quad F_8 = F_2^2 + F_6^5 + F_4^6$$



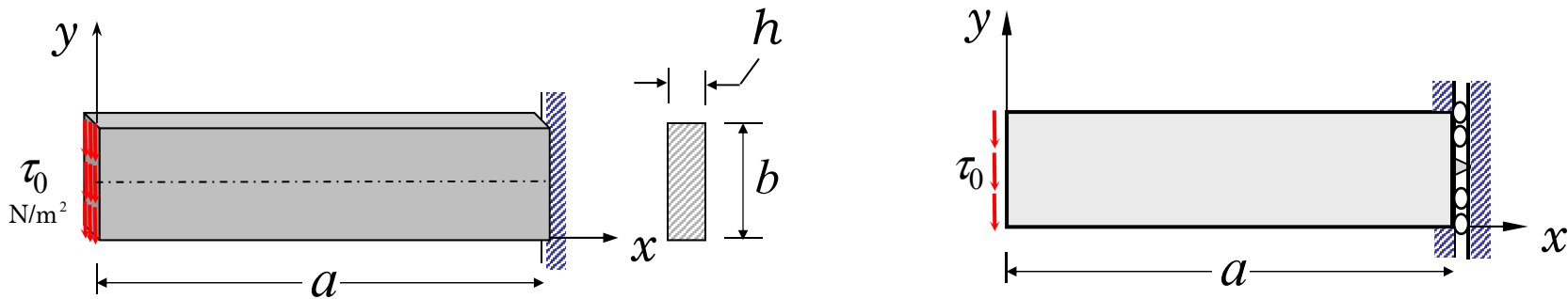
Global



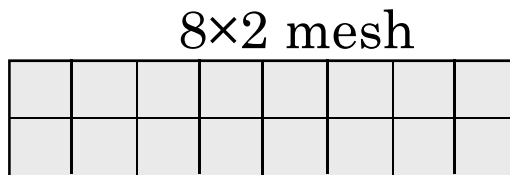
Element

# MODELING ASPECTS: Bending of a cantilever beam

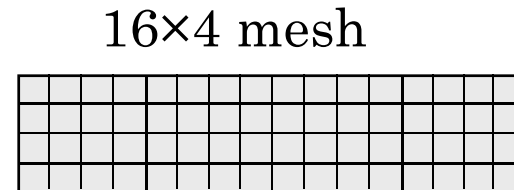
$E = 30 \text{ msi}$ ,  $\nu = 0.25$ ,  $a = 10 \text{ in.}$ ,  $b = 2 \text{ in.}$ ,  $\tau_0 = 150 \text{ psi}$



Beam versus elasticity model



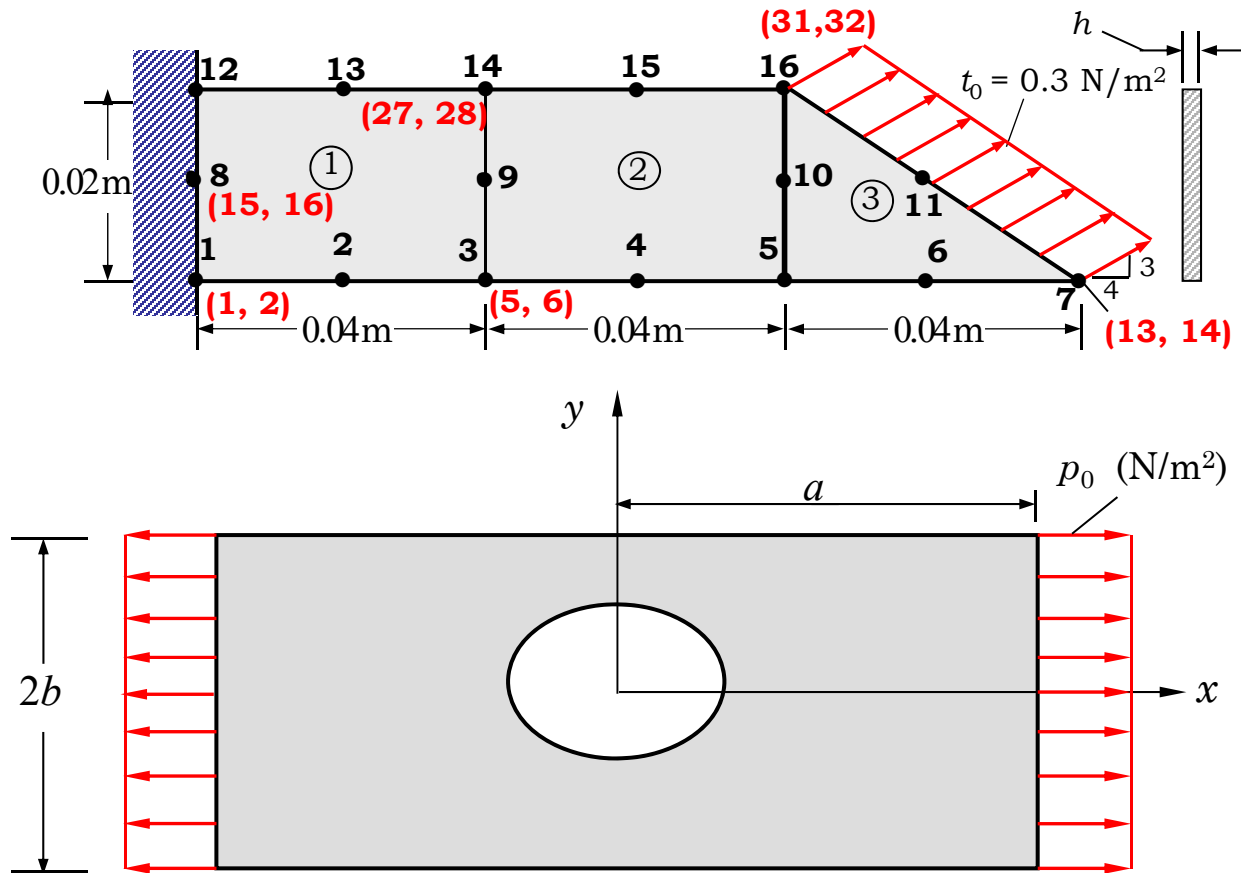
2-D Meshes



$$t_y = -\tau_0 h \text{ N/m at } x = 0$$

# DISCUSSION PROBLEMS

Plane stress  $E_1 = E_2 = 69 \text{ GPa}$ ,  $\nu = 0.333$ ,  $G = 26 \text{ GPa}$ ,  $h = 0.01 \text{ m}$



One quadrant of the domain is used in the finite element analysis (isotropic plate of thickness  $h$ )



# SUMMARY

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In this lecture we have covered the following topics:

- Review of plane stress and plane strain
- Governing equations of plane elasticity
- Finite element models using the weak form
- Static condensation
- Incompatible elements and shear locking
- Discussion problems